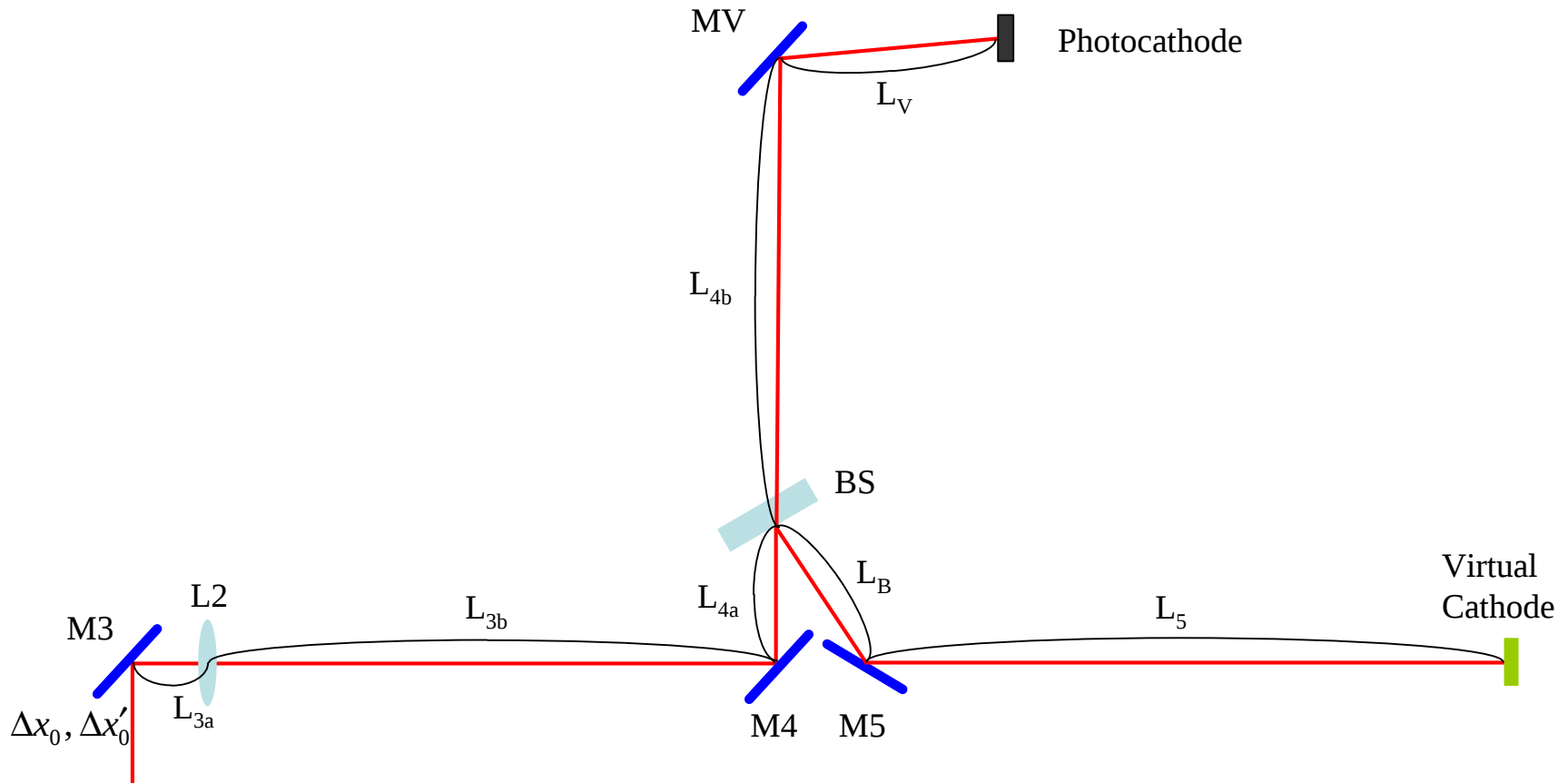


Layout of Optical Components in the Tunnel of PITZ



Numbers from the Draw & Rough Measurement

Numbers in Draw (mm)

$$L_3 = 3162$$

$$L_4 = 3040$$

$$L_V = 655$$

$$f = 7000$$

Assumed Number (mm)

$$L_B + L_5 = L_{4b} + L_V = 3075$$

Measured Numbers (mm)

$$L_{3a} = 130$$

$$L_{3b} = (L_3 - L_{3a}) = 3032$$

$$L_{4a} = 620$$

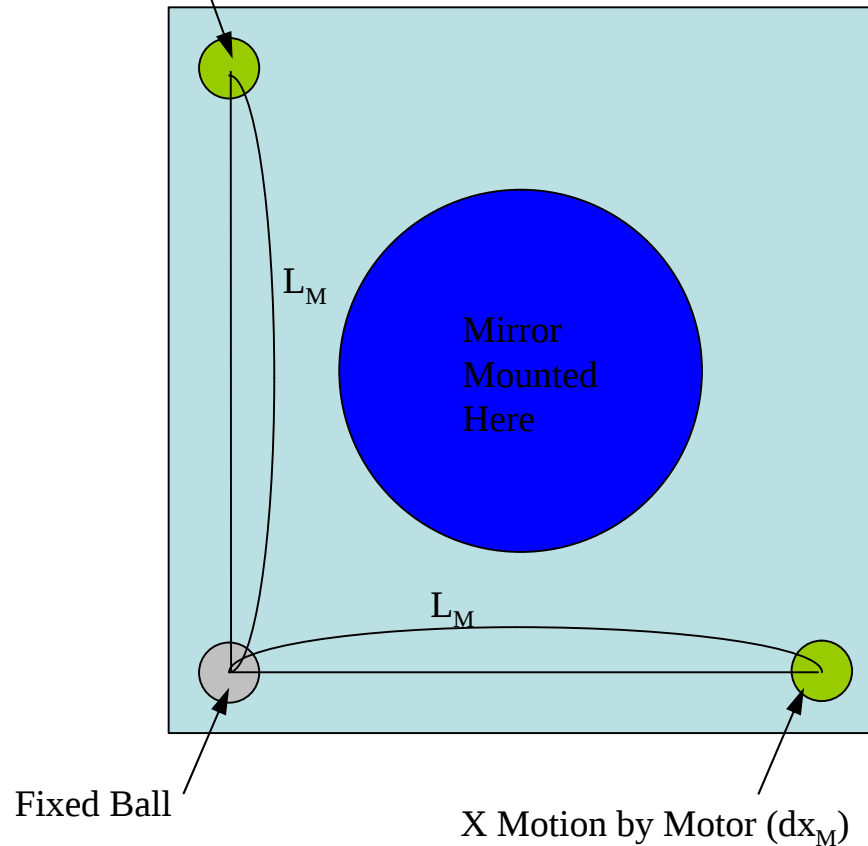
$$L_{4b} = (L_4 - L_{4a}) = 2420$$

$$L_{M3} = 100$$

$$L_{M4} = 160$$

Mechanism of Mirror Movement

Y Motion by Motor (dy_M)



Distance between Movable Points

$$L_{M3}=100$$

$$L_{M4}=160$$

Mirror Diameter

$$M3=50$$

$$M4=75$$

Position & Angle at M4

$$\begin{aligned}
 \Delta x_{M4} = & - \left[1 - \frac{L_{3b}}{f} \right] \Delta x_0 \\
 & - \left[(L_{3a} + L_{3b}) - \frac{L_{3a}L_{3b}}{f} \right] \Delta x'_0 \\
 & + \left[\frac{1}{\sqrt{2}} + \frac{2(L_{3a} + L_{3b})}{L_{M3}} - \frac{L_{3b}}{\sqrt{2}f} - \frac{2L_{3a}L_{3b}}{f L_{M3}} \right] dx_{M3} \\
 & + \left[\frac{1}{2} - \frac{L_{3b}}{2f} \right] dy_{M3}
 \end{aligned}$$

$$\Delta x'_{M4} = \frac{\Delta x_0}{f} - \left(1 - \frac{L_{3a}}{f} \right) \Delta x'_0 + \left(-\frac{1}{\sqrt{2}f} + \frac{2}{L_{M3}} - \frac{2L_{3a}}{fL_{M3}} \right) dx_{M3} - \frac{dy_{M3}}{f}$$

$$\begin{aligned}
\Delta y_{M4} = & \left[1 - \frac{L_{3b}}{f} \right] \Delta y_0 \\
& + \left[(L_{3a} + L_{3b}) - \frac{L_{3a}L_{3b}}{f} \right] \Delta y_0' \\
& - \left[\frac{\sqrt{2}(L_{3a} + L_{3b})}{L_{M3}} - \frac{\sqrt{2}L_{3a}L_{3b}}{f L_{M3}} \right] dy_{M3}
\end{aligned}$$

$$\Delta y_{M4}' = -\frac{\Delta y_0}{f} + \left(1 - \frac{L_{3a}}{f} \right) \Delta y_0' - \left(\frac{\sqrt{2}}{L_{M3}} - \frac{\sqrt{2}L_{3a}}{f L_{M3}} \right) dy_{M3}$$

Position & Angle at MV

$$\begin{aligned}
 \Delta x_{MV} = & \left[1 - \frac{(L_{3b} + L_{4a} + L_{4b})}{f} \right] \Delta x_0 \\
 & + \left[(L_{3a} + L_{3b} + L_{4a} + L_{4b}) - \frac{L_{3a}(L_{3b} + L_{4a} + L_{4b})}{f} \right] \Delta x'_0 \\
 & - \left[\frac{1}{\sqrt{2}} + \frac{2(L_{3a} + L_{3b} + L_{4a} + L_{4b})}{L_{M3}} - \frac{(L_{3b} + L_{4a} + L_{4b})}{\sqrt{2}f} - \frac{2L_{3a}(L_{3b} + L_{4a} + L_{4b})}{f L_{M3}} \right] dx_{M3} \\
 & - \left[\frac{1}{2} - \frac{(L_{3b} + L_{4a} + L_{4b})}{2f} \right] dy_{M3} \\
 & - \left[\frac{1}{\sqrt{2}} - \frac{2(L_{4a} + L_{4b})}{L_{M4}} \right] dx_{M4} \\
 & - \frac{1}{2} dy_{M4}
 \end{aligned}$$

$$\Delta x'_{MV} = -\frac{\Delta x_0}{f} + \left(1 - \frac{L_{3a}}{f} \right) \Delta x'_0 - \left(-\frac{1}{\sqrt{2}f} + \frac{2}{L_{M3}} - \frac{2L_{3a}}{fL_{M3}} \right) dx_{M3} + \frac{dy_{M3}}{f} + \frac{dx_{M4}}{L_{M4}}$$

$$\begin{aligned}
\Delta y_{MV} = & \left[1 - \frac{(L_{3b} + L_{4a} + L_{4b} + L_V)}{f} \right] \Delta y_0 \\
& + \left[(L_{3a} + L_{3b} + L_{4a} + L_{4b}) - \frac{L_{3a}(L_{3b} + L_{4a} + L_{4b})}{f} \right] \Delta y'_0 \\
& - \left[\frac{\sqrt{2}(L_{3a} + L_{3b} + L_{4a} + L_{4b})}{L_{M3}} - \frac{\sqrt{2}L_{3a}(L_{3b} + L_{4a} + L_{4b})}{f L_{M3}} \right] dy_{M3} \\
& - \frac{\sqrt{2}(L_{4a} + L_{4b})}{L_{M4}} dy_{M4}
\end{aligned}$$

$$\Delta y'_{MV} = -\frac{\Delta y_0}{f} + \left(1 - \frac{L_{3a}}{f} \right) \Delta y'_0 - \left(\frac{\sqrt{2}}{L_{M3}} - \frac{\sqrt{2}L_{3a}}{fL_{M3}} \right) dy_{M3} - \frac{\sqrt{2}}{L_{M4}} dy_{M4}$$

Position & Angle at Photocathode

$$\Delta x_{cathode} =$$

$$\begin{aligned}
 & - \left[1 - \frac{(L_{3b} + L_{4a} + L_{4b} + L_V)}{f} \right] \Delta x_0 \\
 & - \left[(L_{3a} + L_{3b} + L_{4a} + L_{4b} + L_V) - \frac{L_{3a}(L_{3b} + L_{4a} + L_{4b} + L_V)}{f} \right] \Delta x'_0 \\
 & + \left[\frac{1}{\sqrt{2}} + \frac{2(L_{3a} + L_{3b} + L_{4a} + L_{4b} + L_V)}{L_{M3}} - \frac{(L_{3b} + L_{4a} + L_{4b} + L_V)}{\sqrt{2}f} - \frac{2L_{3a}(L_{3b} + L_{4a} + L_{4b} + L_V)}{f L_{M3}} \right] dx_{M3} \\
 & + \left[\frac{1}{2} - \frac{(L_{3b} + L_{4a} + L_{4b} + L_V)}{2f} \right] dy_{M3} \\
 & + \left[\frac{1}{\sqrt{2}} - \frac{2(L_{4a} + L_{4b} + L_V)}{L_{M4}} \right] dx_{M4} \\
 & + \frac{1}{2} dy_{M4}
 \end{aligned}$$

$$\Delta y_{cathode} =$$

$$\begin{aligned} & \left[1 - \frac{(L_{3b} + L_{4a} + L_{4b} + L_V)}{f} \right] \Delta y_0 \\ & + \left[(L_{3a} + L_{3b} + L_{4a} + L_{4b} + L_V) - \frac{L_{3a}(L_{3b} + L_{4a} + L_{4b} + L_V)}{f} \right] \Delta y'_0 \\ & - \left[\frac{\sqrt{2}(L_{3a} + L_{3b} + L_{4a} + L_{4b} + L_V)}{L_{M3}} - \frac{\sqrt{2}L_{3a}(L_{3b} + L_{4a} + L_{4b} + L_V)}{f L_{M3}} \right] dy_{M3} \\ & - \frac{\sqrt{2}(L_{4a} + L_{4b} + L_V)}{L_{M4}} dy_{M4} \end{aligned}$$

$$\Delta x'_{cathode} = \frac{\Delta x_0}{f} - \left(1 - \frac{L_{3a}}{f} \right) \Delta x'_0 + \left(-\frac{1}{\sqrt{2}f} + \frac{2}{L_{M3}} - \frac{2L_{3a}}{fL_{M3}} \right) dx_{M3} - \frac{dy_{M3}}{f} - \frac{dx_{M4}}{L_{M4}}$$

$$\Delta y'_{cathode} = -\frac{\Delta y_0}{f} + \left(1 - \frac{L_{3a}}{f} \right) \Delta y'_0 - \left(\frac{\sqrt{2}}{L_{M3}} - \frac{\sqrt{2}L_{3a}}{fL_{M3}} \right) dy_{M3} - \frac{\sqrt{2}}{L_{M4}} dy_{M4}$$

Position & Angle at Virtual Cathode

$$\Delta x_{\text{virtual}} =$$

$$\begin{aligned} & \left[1 - \frac{(L_{3b} + L_{4a} + L_B + L_5)}{f} \right] \Delta x_0 \\ & + \left[(L_{3a} + L_{3b} + L_{4a} + L_B + L_5) - \frac{L_{3a}(L_{3b} + L_{4a} + L_B + L_5)}{f} \right] \Delta x'_0 \\ & - \left[\frac{1}{\sqrt{2}} + \frac{2(L_{3a} + L_{3b} + L_{4a} + L_B + L_5)}{L_{M3}} - \frac{(L_{3b} + L_{4a} + L_B + L_5)}{\sqrt{2}f} - \frac{2L_{3a}(L_{3b} + L_{4a} + L_B + L_5)}{f L_{M3}} \right] dx_{M3} \\ & - \left[\frac{1}{2} - \frac{(L_{3b} + L_{4a} + L_B + L_5)}{2f} \right] dy_{M3} \\ & - \left[\frac{1}{\sqrt{2}} - \frac{2(L_{4a} + L_B + L_5)}{L_{M4}} \right] dx_{M4} \\ & - \frac{1}{2} dy_{M4} \end{aligned}$$

$$\Delta y_{virtual} =$$

$$\begin{aligned} & \left[1 - \frac{(L_{3b} + L_{4a} + L_B + L_5)}{f} \right] \Delta y_0 \\ & + \left[(L_{3a} + L_{3b} + L_{4a} + L_B + L_5) - \frac{L_{3a}(L_{3b} + L_{4a} + L_B + L_5)}{f} \right] \Delta y'_0 \\ & - \left[\frac{\sqrt{2}(L_{3a} + L_{3b} + L_{4a} + L_B + L_5)}{L_{M3}} - \frac{\sqrt{2}L_{3a}(L_{3b} + L_{4a} + L_B + L_5)}{f L_{M3}} \right] dy_{M3} \\ & - \frac{\sqrt{2}(L_{4a} + L_B + L_5)}{L_{M4}} dy_{M4} \end{aligned}$$

$$\Delta x'_{virtual} = -\frac{\Delta x_0}{f} + \left(1 - \frac{L_{3a}}{f} \right) \Delta x'_0 - \left(-\frac{1}{\sqrt{2}f} + \frac{2}{L_{M3}} - \frac{2L_{3a}}{fL_{M3}} \right) dx_{M3} + \frac{dy_{M3}}{f} + \frac{dx_{M4}}{L_{M4}}$$

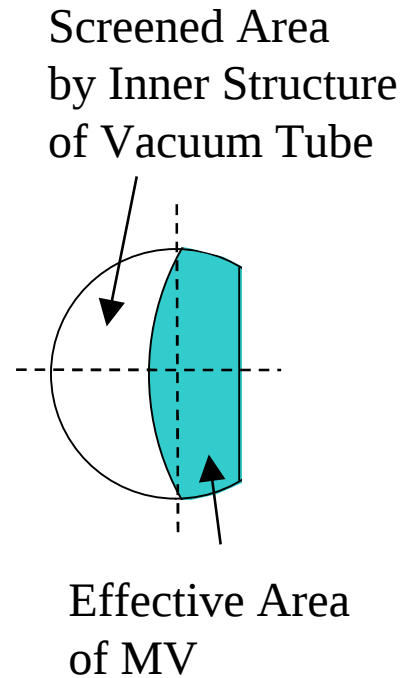
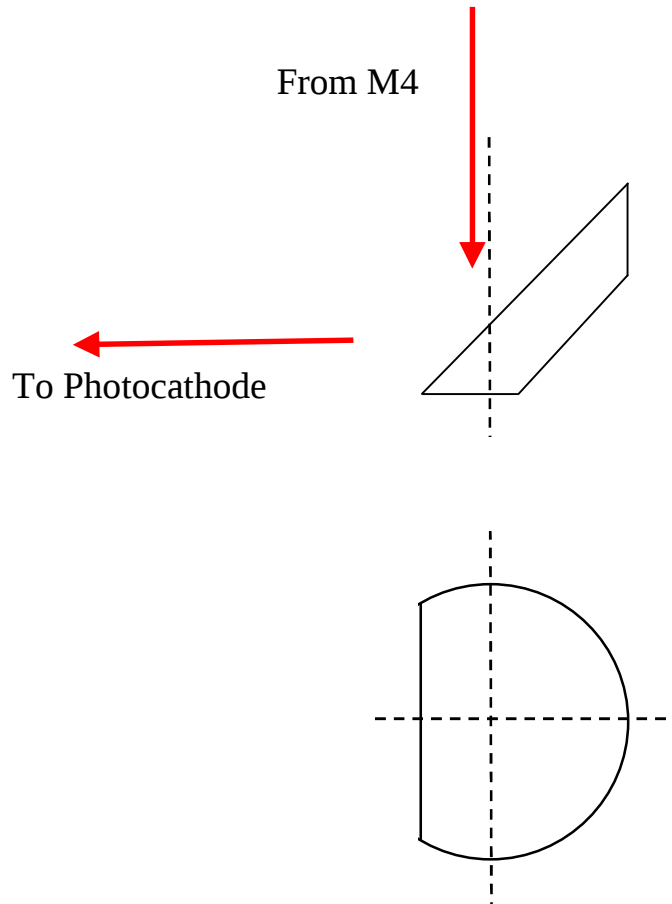
$$\Delta y'_{virtual} = -\frac{\Delta y_0}{f} + \left(1 - \frac{L_{3a}}{f} \right) \Delta y'_0 - \left(\frac{\sqrt{2}}{L_{M3}} - \frac{\sqrt{2}L_{3a}}{fL_{M3}} \right) dy_{M3} - \frac{\sqrt{2}}{L_{M4}} dy_{M4}$$

Position Variations Resulted from Initial Position & Angle Offset of the Laser Beam and the Movement of Mirrors

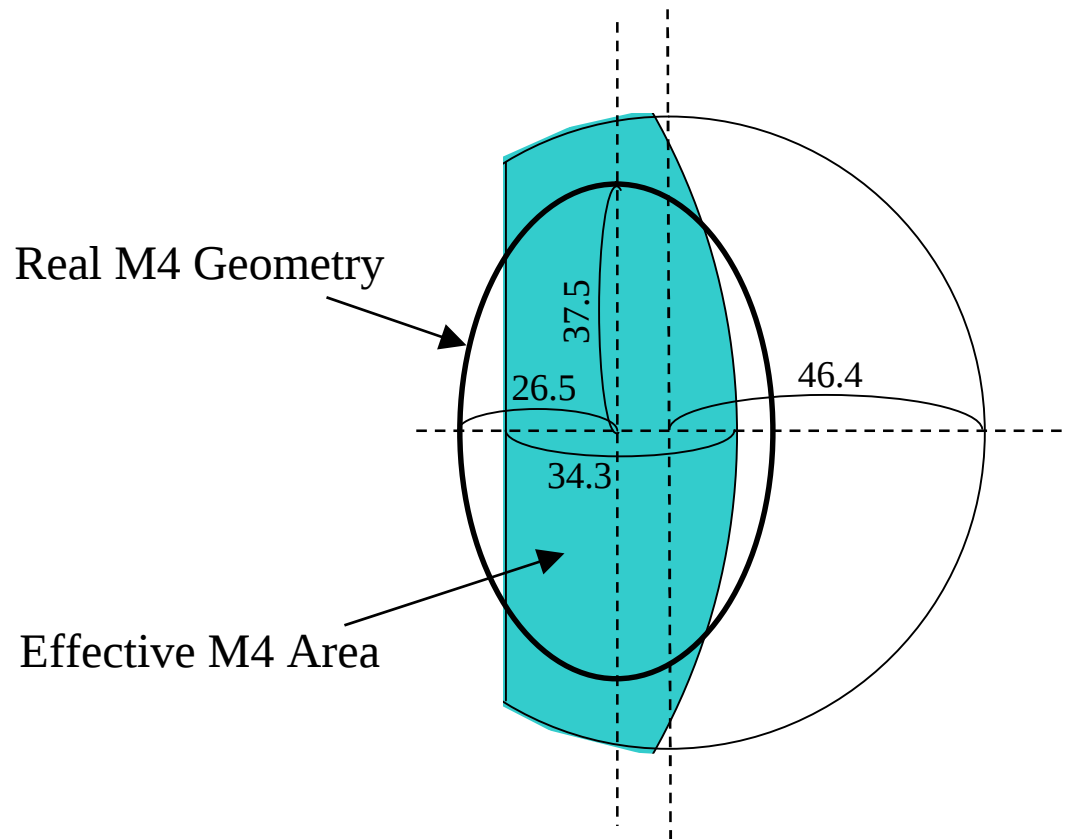
	x_0	x'_0	dx_{M3}	dy_{M3}	dx_{M4}	dy_{M4}
x_{M4}	-0.57	-3106	62.5	0.28		
x_{MV}	0.13	6089	-122	-0.07	37.3	-0.5
$x_{cathode}$	-0.04	-6732	135	0.02	-45	0.5
$x_{virtual}$	0.04	6732	-135	-0.02	45	-0.5

	y_0	y'_0	dx_{M3}	dy_{M3}	dx_{M4}	dy_{M4}
y_{M4}	0.57	3106	0	-43.9		
y_{MV}	0.13	6089	0	-84.7	0	-26.9
$y_{cathode}$	0.04	6732	0	-98	0	-32.5
$y_{virtual}$	0.04	6732	0	-98	0	-32.5

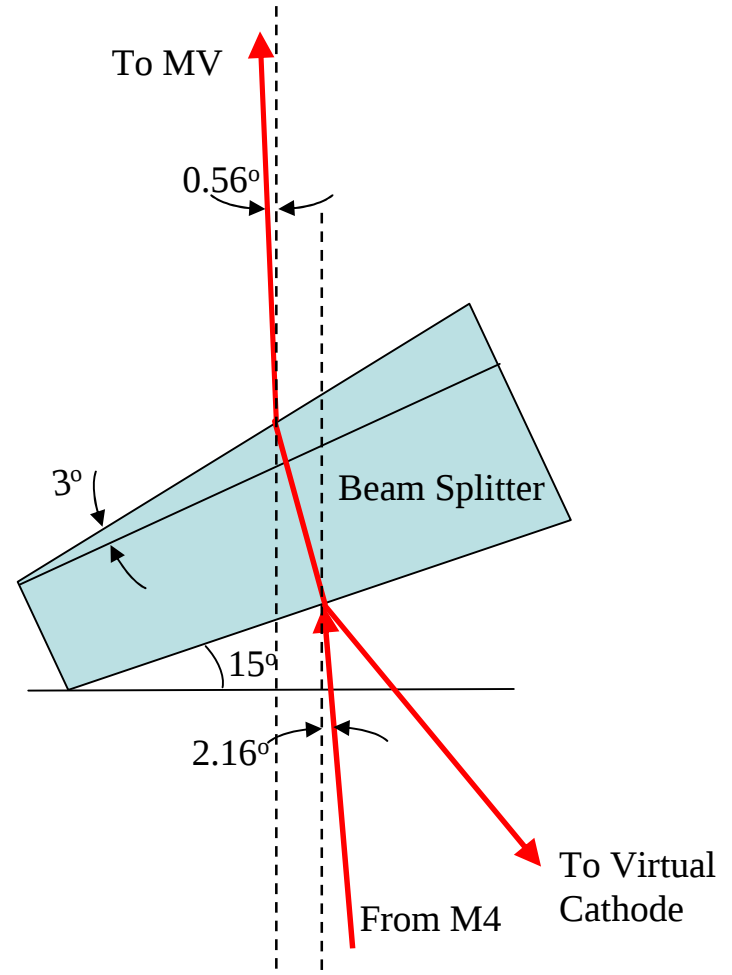
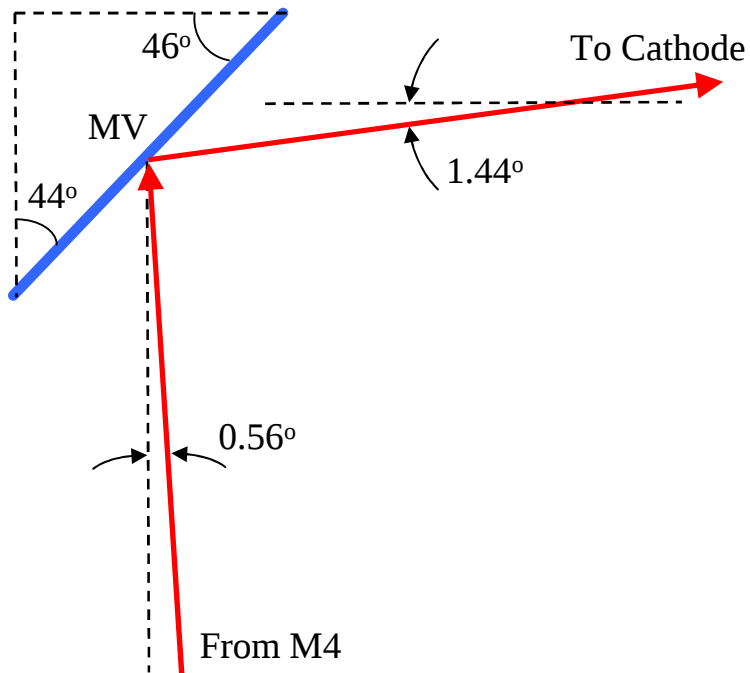
Description on MV



Effective Area of M4



Laser Motion at MV & Beam Splitter



Optimum Position & Angle of M4

