



Information Processing with Pulsed Neural Networks

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Dilemma (1)



Prof. Ramacher, CPR ST 25-May-05 Page 2

lack of robustness





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lack of architecture information



Dilemma (3)



- Non-invasive long-term recording of neural tissue.
- High-density sensor with 128×128 Sensors in 1×1mm².
- Extended CMOS-process with biocompatible high-k surface dielectric.
- Self-calibration circuitry and pre-amplification on chip.
- Applications in **neurobiology** and **drug discovery**

Infineon Neurochip





Prof. Ramacher, CPR ST 25-May-05 Page 4

Gap between signal processing by few cells and information processing by large arrays



Program



- 1. Use pulsed IAF neurons and adaptive synapses (inhibitory, excitatory)
- 2. Use experimental evidence
- 3. Start from simple, complete vision systems
- 4. Find basic network structures for information processing
- 5. Find quantitative ansatz for information processing
- 6. Demonstrate usefulness for cell phones



Neuron Model

$$k \in R(t_0): \quad a_k(t) = a_k(t_0) + \int_{t_0}^t \left[\sum_{l \in S(t_0)} W_{kl}(t') \cdot X_l(t') + W_{k0} \cdot i_k(t') \right] dt'$$

or :

$$da_{k}/dt = -c \cdot a_{k}(t) + \sum_{l \in S(t_{0})} W_{kl}(t) \cdot X_{l}(t) + W_{k0} \cdot i_{k}(t)$$

- Rule 1: Reaching the threshold, a neuron resets membrane potential to zero and starts sending a pulse of 1 ms
- Rule 2: A neuron either receives or sends

➔ deterministic dynamical system



Experiment 1





Experiment 1





 \rightarrow

Observations

- "Firing patterns don't come to an end"
- information processing is not a function of time

Does frequency of firing patterns characterize the net ? $I_{net} = -\sum p_n x \ln p_n$

Is entropy a reproducible measure of information?



Experiment 2:





Experiment 2







$$\rightarrow$$
 I_{net} = - $\sum p_n x \ln p_n$

is a reproducibly measurable quantity

Entropy as a function of mean synaptic weight

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Network size: 40 neurons



ISI

Fire Rate

Prof. Ramacher, CPR ST 25-May-05 Page 14

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Synapse Model (proposed by U. Ramacher, April 99)

$k \in E(t_0), l \in S(t_0)$:

$$\dot{W}_{kl} = -\gamma \cdot W_{kl} + \mu \cdot \left(a_k(t) - \frac{\theta}{2}\right) \cdot \chi(X_l)$$

else:
$$\dot{W}_{kl} = -\gamma \cdot W_{kl}$$

Adaptation rule : local, causal, simple

$$\ddot{W}_{kl} + \gamma \cdot \dot{W}_{kl} - \mu \cdot W_{kl}(t') \cdot X_l =$$
$$\mu \cdot \left(\sum_{l' \in S(t_0)} W_{kl'}(t') \cdot X_{l'} + W_{k0} \cdot i_k(t') + a_k(t_0) - \frac{\theta}{2} \right)$$

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µ negative

- 20 x 24 pixels, each connected to a neuron by a constant synapse
- adaptive synapses connecting neighboured neurons



synapses = coupled system of damped oscillators



µ positive

20x24 pixel, 10% noise



synapses = coupled system of damped
exponentially rising and falling "elements"



Spot Detector = Illumination Encoder







25-May-05 Page 19





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convergence



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Modeling the Experiment



Prof. Ramacher, CPR ST 25-May-05 Page 22

 Π : measured pulse rate **G**_i: Gabor function **H**: Spot Intensity **B**: Background Intensity



Pulse difference detector (1)





Pulse difference detector (2)



Dynamics of the Synapse W_{41} :

 $\frac{dW_{KL}}{dt} = -\gamma \cdot (W_{KL} - W_{\infty}) + \mu \cdot (I_{pre} - I_{\theta}) \cdot W_{KL} \cdot \chi(X_L)$

$$\mu < 0$$
 , $I_{pre} - I_g > 0$, $W_{KL} \ge 0$



Pulse difference detector (3)





Characteristic



 $\begin{array}{ll} \textbf{i_1} & = \textbf{0.5} \\ \Theta & = 1 \\ W_{K0} = 0.08 \\ \textbf{t}_d & = 1 ms \\ T & = 0.5s \end{array}$



Architecture of feature detector

(proposed by A. Heittmann, 2003)







Shaping the response-profile of the detector



 $N_{i}^{1}(x_{0}, y_{0}) = \iint_{(x_{0}, x_{0} + \Delta x) \times (y_{0}, y_{0} + \Delta y)} \rho_{i}^{1}(x, y) dx dy$ $N_{i}^{2}(x_{0}, y_{0}) = \iint \rho_{i}^{2}(x, y) dx dy$ $(x_0, x_0 + \Delta x) \times (y_0, y_0 + \Delta y)$

section of the retina

$$\Pi(x_{0}, y_{0}) = \frac{W_{K0}}{\Theta} \cdot (H - B)(N_{i}^{1}(x_{0}, y_{0}) - N_{i}^{2}(x_{0}, y_{0}))$$

$$\approx (H - B) \cdot \iint G_{i}(x, y) dx dy$$

$$\Rightarrow \rho_i^1(x, y) - \rho_i^2(x, y) = \frac{\Theta}{W_{K0}} G_i(x, y)$$

H: Spot Intensity B: Background Intensity





Simulated Filter responses, T=750ms







The Head-Detector



Restriction

- single scale (keep eye-distance fixed)



Check for Robustness in Eye-Brow Zone

Reference Image

Filter Response, horizontal direction

region of interest





20x20 Pixel



new eye-brow image



A simple memory (1), 1 zone

Learning Phase
$$\dot{W}_{KL} = -\gamma W_{KL} + \mu \cdot \left(a_K - \frac{\theta}{2}\right) \cdot \chi(X_L) \cdot \exp\left(-\left(\pi_K(t) - \pi_L(t)\right)^2 / \pi_L^2(t)\right)$$



Prof. Ramacher, CPR ST 25-May-05 Page 32

Input Layer

full connection between detector and memory layer



Experiment 1: learned image in input and memory

Activity (number of events), 2ms window



Pulse-patterns of input-layer



A simple memory (2), 1 Zone

Recognition Phase
$$\dot{W}_{KL} = -\gamma W_{KL} + \mu \cdot \left(a_K - \frac{\theta}{2}\right) \cdot \chi(X_I) \cdot \exp\left(-\left(\pi_{K,M} - \pi_L(t)\right)^2 / \pi_L^2(t)\right)$$



Prof. Ramacher, CPR ST 25-May-05 Page 34

Gabor Layer

full connection between detector and memory layer



Experiment 3: recognition of non-learned eye-brow

Activity (number of events), 2ms window



Pulse-patterns of input-layer



Experiment 2: Isolated neurons

Activity (number of events), 2ms window



Pulse-patterns of input-layer



Zone-Architecture I





Zone-Architecture II



Zuordnung: Zonen zu Bildregionen



: Zone für Gabor-Wavlet mit horizontaler Orientierung

: Zone für Gabor-Wavlet mit vertikaler Orientierung



Reference-Image and Test-Images

Reference-Image:



Test-Images:



Face 0001





Face 0014



Face 0001





Video Clip

Activity-Diagram







Activity-Diagram





Normalized accumulated activity





Face 0014





Activity-Diagram





Binding of zones by synchrony







Column Architecture





The vision: a 3D-Vision-Cube

The Vision-Cube



• 3D-stacking-architecture

- Low-power
- Real time capabilities
- Integration of sensors and information processing
- Distributes layers of information processing to layers of the stack
- Solves problem of connectivity



Design of a testchip for the "Synchrony detector", Base-Chip for the 3D-Stack





Gabor-Feature-Detector chip (layout) including a pulse router for the 3D-integration





3D-Stacking





Real 3D !!





Conclusion

- IAF neurons, adaptive synapses, only
- network built for
 - -- Gabor wavelet based feature cascade
 - -- memory
 - -- comparison of memory and detector plane
- synchrony of neurons indicative for
 - -- robust recognition of memory feature at detector plane (elastic matching)
 - -- binding of features as object
- built in 130 nm CMOS
 - -- synchrony detector
 - -- Gabor wavelet detector
 - -- 3 D stack of 7 silicon chips