

# Luminosity stabilization at TESLA photon collider

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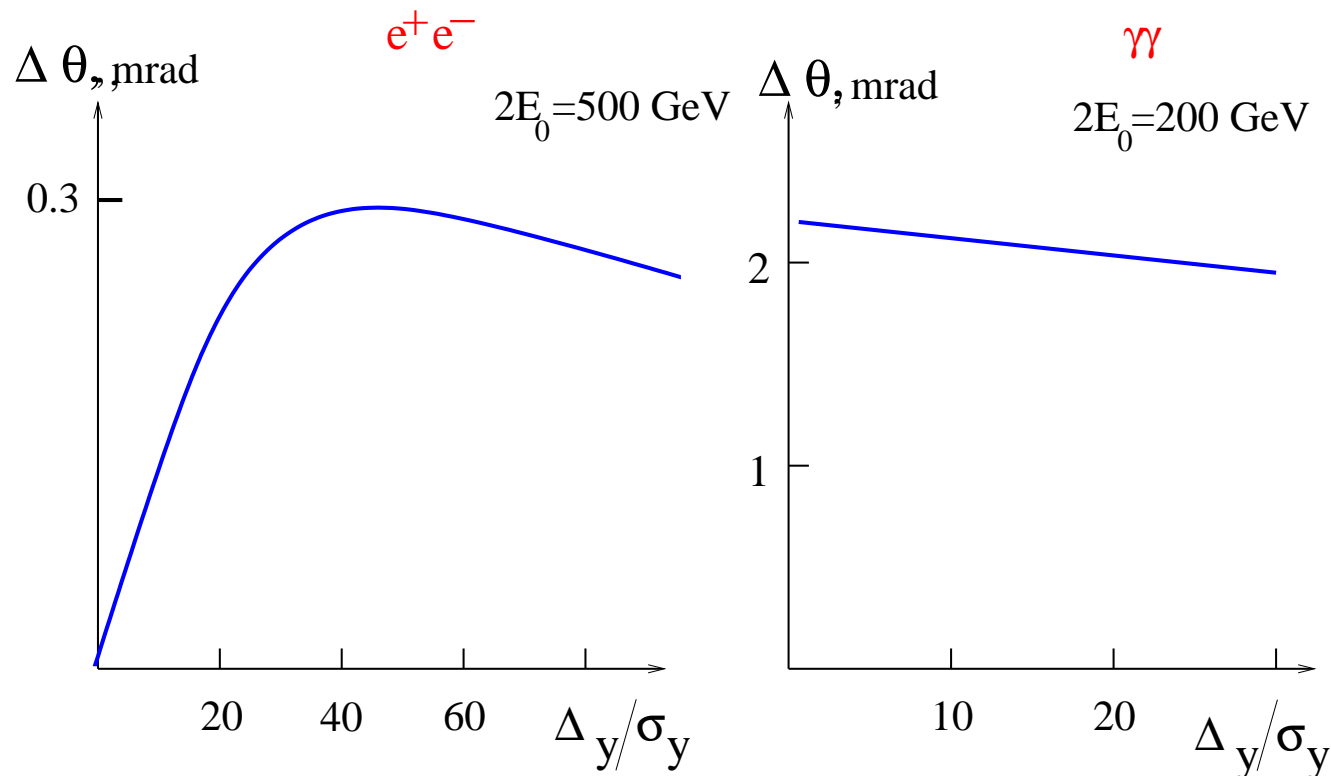
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Beam collisions at linear colliders can be controlled by the beam beam deflection.

Difference between  $e^+e^-$  and  $\gamma\gamma$  cases:

1. In the  $e^+e^-$  case, at small vertical displacement the beams attract and oscillate inside each other. In  $\gamma\gamma$  case ( $e^-e^-$ ) as well) the beams repel each other. As result the deflection angle is larger.
2. In  $\gamma\gamma$  collisions  $\sigma_x$  is several times smaller than in  $e^+e^-$  case ( $\sim 5$  times at TESLA). The kick is much larger then in  $e^+e^-$  and almost independent on the initial displacement.



## Dependence of the deflection angle on beam parameters

For small deflections, when the vertical beam displacement during the beam collision is less than  $\sigma_x$

$$\vartheta_y \sim \frac{\sigma_z}{R}; \quad R \sim \frac{pc}{eB}; \quad B \sim \frac{2eN}{\sigma_x \sigma_z}$$
$$\implies \vartheta_y \sim \frac{2r_e N}{\sigma_x \gamma},$$

this is valid for  $\vartheta_y < \sigma_x / \sigma_z$ .

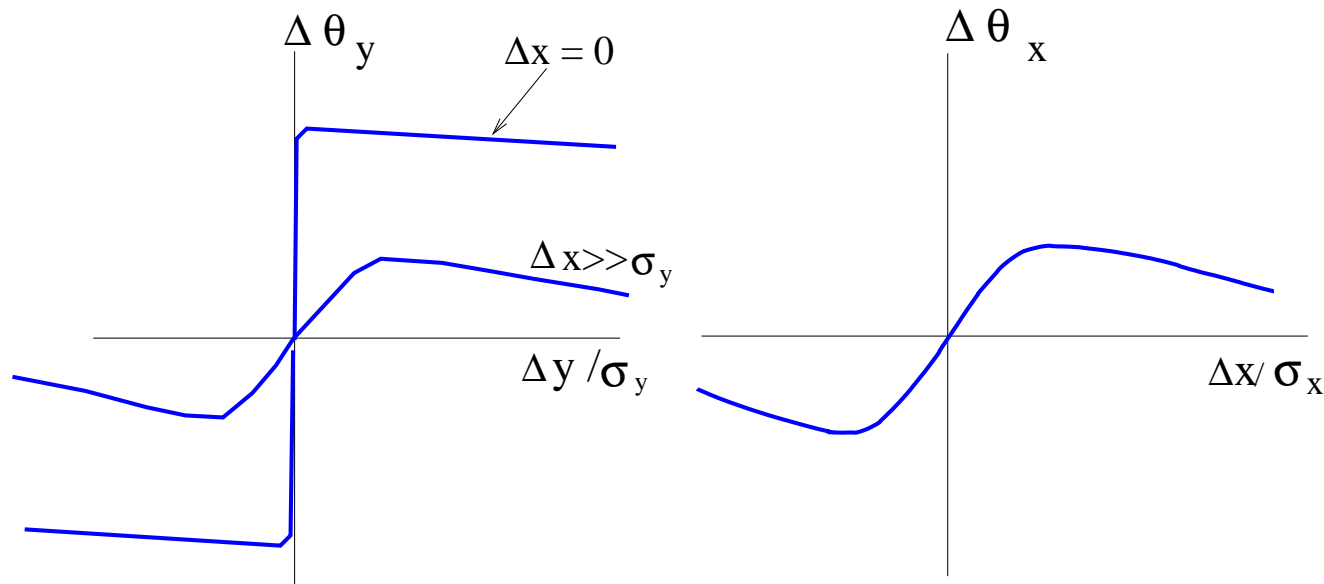
For large deflections (the case for low energy photon colliders, including TESLA  $2E = 500$  GeV)

$$\frac{R\vartheta_y^2}{2} \sim 2\sigma_x \implies \vartheta_y \sim \sqrt{\frac{4\pi N r_e}{\sigma_z \gamma}},$$

valid for  $\vartheta_y > \sigma_x / \sigma_z$ . The deflection does not depend on  $\sigma_x$  and  $\sigma_y$ .

At photon colliders about half of particles have  $E \sim 0.1 - 0.2E_0$  and essentially influence  $\overline{\vartheta_y}$ .

$\gamma\gamma$  — the general case



The main difference from  $e^+e^-$  is the **step-like behavior** of the  $\vartheta_y$  on the displacement  $\Delta_y$ . This function depends on the conversion efficiency.

**Prescription:** the feedback system for  $\gamma\gamma$  is similar to  $e^+e^-$ , but somewhat different algorithm (for the vertical direction). Varying the beam position one should find the jump and continuously go up and down around this place by small displacements  $\Delta_y \ll \sigma_y$ . Zero points for the pickups can be found by sending only one beam to the IP.